

# Euler-Maclaurin formula and generalised iterated integrals

Carlo Bellingeri

With

P. Friz (TU Berlin & WIAS)

S. Paycha (Potsdam University)

Algebraic, analytic and geometric structures emerging from  
quantum field theory

11.03.2024



# The Euler-Maclaurin Formula

For any  $f : [0, N] \rightarrow \mathbb{R}$  of class  $C^p$  we have

$$(EML) \quad \sum_{k=0}^{N-1} f(k) = \int_0^N f(s) ds + \sum_{k=1}^p \frac{B_k}{k!} [f^{(k-1)}(s)]_{s=0}^N + R_p$$

$B_k$  Bernoulli numbers  $1, -\frac{1}{2}, \frac{1}{6}, 0, -\frac{1}{30}, 0, \dots$

$R_p$  Remainder which depends linearly on  $f^{(p)}$ .

This identity links integrals to sums, leading to many results in mathematics: complex analysis, operator theory, numerical analysis.

What happens in a stochastic framework with Riemann-Stieltjes integration?

# The Euler-Maclaurin Formula

For any  $f : [0, N] \rightarrow \mathbb{R}$  of class  $C^p$  we have

$$(EML) \quad \sum_{k=0}^{N-1} f(k) = \int_0^N f(s) ds + \sum_{k=1}^p \frac{B_k}{k!} [f^{(k-1)}(s)]_{s=0}^N + R_p$$

$B_k$  **Bernoulli numbers**  $1, -\frac{1}{2}, \frac{1}{6}, 0, -\frac{1}{30}, 0, \dots$

$R_p$  **Remainder** which depends **linearly** on  $f^{(p)}$ .

This identity links **integrals** to **sums**, leading to many results in mathematics: complex analysis, operator theory, numerical analysis.

What happens in a stochastic framework with **Riemann-Stieltjes** integration?

# The Euler-Maclaurin Formula

For any  $f : [0, N] \rightarrow \mathbb{R}$  of class  $C^p$  we have

$$(EML) \quad \sum_{k=0}^{N-1} f(k) = \int_0^N f(s) ds + \sum_{k=1}^p \frac{B_k}{k!} [f^{(k-1)}(s)]_{s=0}^N + R_p$$

$B_k$  **Bernoulli numbers**  $1, -\frac{1}{2}, \frac{1}{6}, 0, -\frac{1}{30}, 0, \dots$

$R_p$  **Remainder** which depends **linearly** on  $f^{(p)}$ .

This identity links **integrals** to **sums**, leading to many results in mathematics: complex analysis, operator theory, numerical analysis.

What happens in a stochastic framework with **Riemann-Stieltjes** integration?

# The Euler-Maclaurin Formula

(*EML*) is justified on the basis of **three basic identities**

- The sum  $\sum$  and the integration  $\int$  are the inverse operators of

$$\delta f(x) = f(x+1) - f(x), \quad Df(x) = f'(x).$$

- The formal expansion

$$\delta f(x) = \sum_{k \geq 1} \frac{f^{(k)}(x)}{k!} = \sum_{k \geq 1} \frac{D^k}{k!} f(x) = (e^D - \text{id})f(x)$$

- The formal expansion of the integral  $\int_a^b f(x) dx$  is
- $$\int_a^b f(x) dx = \int_a^b \sum_{k \geq 0} \frac{D^k}{k!} f(x) dx = \sum_{k \geq 0} \frac{D^k}{k!} \int_a^b f(x) dx$$

# The Euler-Maclaurin Formula

(*EML*) is justified on the basis of **three basic identities**

- The sum  $\sum$  and the integration  $\int$  are the **inverse operators** of

$$\delta f(x) = f(x+1) - f(x), \quad Df(x) = f'(x).$$

- The **formal** expansion

$$\delta f(x) = \sum_{k \geq 1} \frac{f^{(k)}(x)}{k!} = \sum_{k \geq 1} \frac{D^k}{k!} f(x) = (e^D - \text{id})f(x)$$

- The **series** expansion

$$\frac{z}{e^z - 1} = \sum_{k \geq 0} \frac{B_k}{k!} z^k$$

# The Euler-Maclaurin Formula

(*EML*) is justified on the basis of **three basic identities**

- The sum  $\sum$  and the integration  $\int$  are the **inverse operators** of

$$\delta f(x) = f(x+1) - f(x), \quad Df(x) = f'(x).$$

- The **formal** expansion

$$\delta f(x) = \sum_{k \geq 1} \frac{f^{(k)}(x)}{k!} = \sum_{k \geq 1} \frac{D^k}{k!} f(x) = (e^D - \text{id})f(x)$$

- The series expansion

$$\frac{z}{e^z - 1} = \sum_{k \geq 0} \frac{B_k}{k!} z^k$$

# The Euler-Maclaurin Formula

(*EML*) is justified on the basis of **three basic identities**

- The sum  $\sum$  and the integration  $\int$  are the **inverse operators** of

$$\delta f(x) = f(x+1) - f(x), \quad Df(x) = f'(x).$$

- The **formal** expansion

$$\delta f(x) = \sum_{k \geq 1} \frac{f^{(k)}(x)}{k!} = \sum_{k \geq 1} \frac{D^k}{k!} f(x) = (e^D - \text{id})f(x)$$

- The series expansion

$$\frac{z}{e^z - 1} = \sum_{k \geq 0} \frac{B_k}{k!} z^k$$



# The Euler-Maclaurin Formula

By combining these three facts

$$\begin{aligned}\sum &= \delta^{-1} = (e^D - \text{id})^{-1} = D^{-1} \frac{D}{e^D - \text{id}} \\ &= D^{-1} + \sum_{k \geq 1} \frac{B_k}{k!} D^{k-1} = \int + \sum_{k \geq 1} \frac{B_k}{k!} D^{k-1}\end{aligned}$$

This approach does not take account of **boundary terms**.

Using this approach, classical sums can be replaced by a generic sum over the vertices of a polytope [Berline-Vergne '18] and other generalizations

# The Euler-Maclaurin Formula

By combining these three facts

$$\begin{aligned}\sum &= \delta^{-1} = (e^D - \text{id})^{-1} = D^{-1} \frac{D}{e^D - \text{id}} \\ &= D^{-1} + \sum_{k \geq 1} \frac{B_k}{k!} D^{k-1} = \int + \sum_{k \geq 1} \frac{B_k}{k!} D^{k-1}\end{aligned}$$

This approach does not take account of **boundary terms**.

Using this approach, classical sums can be replaced by a generic sum over the vertices of a polytope [Berline-Vergne '18] and other generalizations

# An alternative proof

The same formula can be proved as a specific case of a **family** of EML-type formulas [Boas '77]

The key point is to rewrite the sum as a **Stieltjes integral**.

$$\sum_{k=0}^{N-1} f(k) = \int_{-a}^{N-a} f(s) d[s] \quad 0 < a < 1$$

Applying an integration by parts with the function  $P_1(s) = s - [s]$

$$\begin{aligned} \sum - \int &= - \int_{-a}^{N-a} f(s) d(P_1(s)) \\ &= [-f(s)P_1(s)]_{-a}^{N-a} + \int_{-a}^{N-a} f'(s)P_1(s) ds \end{aligned}$$

What happens if we **iterate the integration**?

# An alternative proof

The same formula can be proved as a specific case of a **family** of EML-type formulas [Boas '77]

The key point is to rewrite the sum as a **Stieltjes integral**.

$$\sum_{k=0}^{N-1} f(k) = \int_{-a}^{N-a} f(s) d[s] \quad 0 < a < 1$$

Applying an integration by parts with the function  $P_1(s) = s - [s]$

$$\begin{aligned} \sum - \int &= - \int_{-a}^{N-a} f(s) d(P_1(s)) \\ &= [-f(s)P_1(s)]_{-a}^{N-a} + \int_{-a}^{N-a} f'(s)P_1(s) ds \end{aligned}$$

What happens if we **iterate the integration**?

# An alternative proof

For any sequence of functions  $(P_k)_{k \geq 1}$  s.t.  $P'_k = P_{k-1}$  we have

$$\sum = \int + \sum_{l=1}^p (-1)^l [f^{(l-1)}(s) P_l(s)]_{-a}^{N-a} + (-1)^{p+1} \int_{-a}^{N-a} f^{(p)}(s) P_p(s) ds$$

Sending  $a \downarrow 0$ , one has **EML formula** modulo **initial constants**

The classic choice is to consider  $P = (Q_k)_{k \geq 1}$  s.t.

$$\begin{cases} Q'_k = Q_{k-1} \\ Q_1 = t - [t] - \frac{1}{2} \\ Q_k \text{ 1-periodic, } \int_0^1 Q_k(s) ds = 0 \end{cases}$$

The system identifies a **unique solution** such that  $Q_k(0) = \frac{B_k}{k!}$ .  
Functions  $Q_k$  are called **periodic Bernoulli polynomials**.

# An alternative proof

For any sequence of functions  $(P_k)_{k \geq 1}$  s.t.  $P'_k = P_{k-1}$  we have

$$\sum = \int + \sum_{l=1}^p (-1)^l [f^{(l-1)}(s) P_l(s)]_{-a}^{N-a} + (-1)^{p+1} \int_{-a}^{N-a} f^{(p)}(s) P_p(s) ds$$

Sending  $a \downarrow 0$ , one has **EML formula** modulo **initial constants**

The classic choice is to consider  $P = (Q_k)_{k \geq 1}$  s.t.

$$\begin{cases} Q'_k = Q_{k-1} \\ Q_1 = t - [t] - \frac{1}{2} \\ Q_k \text{ 1-periodic, } \int_0^1 Q_k(s) ds = 0 \end{cases}$$

The system identifies a **unique solution** such that  $Q_k(0) = \frac{B_k}{k!}$ .  
Functions  $Q_k$  are called **periodic Bernoulli polynomials**.

# Extension to Stieltjes Integrals

Let  $X: [0, M] \rightarrow V$  be a **finite variation process** and  $f: V \rightarrow L(V, W)$  a **smooth function** with  $V, W$  Banach spaces. We consider the **Riemann-Stieltjes integral**.

$$\int_0^N f(X_s) dX_s$$

we want to compare it with **Riemann-Stieltjes** sums

$$I_N(f, X) := \sum_{k=0}^{N-1} f(X_k) \delta X_k, \quad \delta X_k = X_{k+1} - X_k$$

Is there a way of deriving a formula between these two operators?  
**Yes**, but we must use the Boas approach.

# Extension to Stieltjes Integrals

Let  $X: [0, N] \rightarrow V$  be a **finite variation process** and  $f: V \rightarrow L(V, W)$  a **smooth function** with  $V, W$  Banach spaces. We consider the **Riemann-Stieltjes integral**.

$$\int_0^N f(X_s) dX_s$$

we want to compare it with **Riemann-Stieltjes** sums

$$I_N(f, X) := \sum_{k=0}^{N-1} f(X_k) \delta X_k, \quad \delta X_k = X_{k+1} - X_k$$

Is there a way of deriving a formula between these two operators?  
**Yes**, but we must use the Boas approach.



# Extension to Stieltjes Integrals

Thanks to the finite variation we write

$$\sum_{k=0}^{N-1} f(X_k)(X_{k+1} - X_k) = \int_{-a}^{N-a} f(X_s) dX_{[s+1]}$$

Using the notation  $Z_s^1 = X_s - X_{[s+1]}$  we repeat

$$\begin{aligned} I_N(f, X) - \int_{-a}^{N-a} f(X_s) dX_s &= - \int_{-a}^{N-a} f(X_s) d(Z_s^1 + b^1) \\ &= -[f(X_s)(Z_s^1 + b^1)]_{-a}^{N-a} + \int_{-a}^{N-a} Df(X_s)(dX_s \otimes Z_s^1 + b^1) ds \end{aligned}$$

By iterating this integration by parts, we obtain a sequence of non-linear **path functionals on  $X$** .

# Extension to Stieltjes Integrals

Thanks to the finite variation we write

$$\sum_{k=0}^{N-1} f(X_k)(X_{k+1} - X_k) = \int_{-a}^{N-a} f(X_s) dX_{[s+1]}$$

Using the notation  $Z_s^1 = X_s - X_{[s+1]}$  we repeat

$$\begin{aligned} I_N(f, X) - \int_{-a}^{N-a} f(X_s) dX_s &= - \int_{-a}^{N-a} f(X_s) d(Z_s^1 + b^1) \\ &= -[f(X_s)(Z_s^1 + b^1)]_{-a}^{N-a} + \int_{-a}^{N-a} Df(X_s)(dX_s \otimes Z_s^1 + b^1) ds \end{aligned}$$

By iterating this integration by parts, we obtain a sequence of non-linear **path functionals on  $X$** .

For each  $f: V \rightarrow L(V, W)$  we write the **gradient**

$$D^p f: V \rightarrow L(V^{\otimes p+1}, W)$$

To keep track of higher order tensors, we use **unitary tensor space**

$$T_1((V)) = \mathbf{1} \oplus \prod_{i=1} V^{\otimes i}, \quad T_1^p(V) = \mathbf{1} \oplus \bigoplus_{i=1}^p V^{\otimes i}$$

with its **applications of projections**  $\pi_i: T_1((V)) \rightarrow V^{\otimes i}$  and its **inverse application**  $v \rightarrow v^{-1}$ .

For each  $f: V \rightarrow L(V, W)$  we write the **gradient**

$$D^p f: V \rightarrow L(V^{\otimes p+1}, W)$$

To keep track of higher order tensors, we use **unitary tensor space**

$$T_1((V)) = \mathbf{1} \oplus \prod_{i=1} V^{\otimes i}, \quad T_1^p(V) = \mathbf{1} \oplus \bigoplus_{i=1}^p V^{\otimes i}$$

with its **applications of projections**  $\pi_i: T_1((V)) \rightarrow V^{\otimes i}$  and its **inverse application**  $v \rightarrow v^{-1}$ .

## Definition (B., Friz, Paycha '24+)

For any  $b \in T_1((V))$ , we consider the finite variation process  $Z(b): [0, N] \rightarrow T_1((V))$  given by

$$\pi_1(Z_t(b)) = X_t - X_{[t+1]} + \pi_1(b)$$

and the *higher order components* satisfy for all  $k \geq 2$  the differential equations

$$\begin{cases} d\pi_k(Z_t(b)) = dX_t \otimes \pi_{k-1}(Z_t(b)) \\ Z_0(b) = \pi_k(b) \end{cases}$$

We call  $Z(b)$  the *sawtooth signature with initial data*  $b$ .

## Proposition (B., Friz, Paycha '24+)

For any  $b \in T_1^P(V)$

$$I_N(f, X) = \int_0^N f(Y_t) dX_t - [f(X_t) b^1]_{t=0}^N \\ + \sum_{l=2}^P (-1)^l [D^{l-1} f(X_t) \pi_l(Z_t(b))]_{t=0}^N + R^P(b)$$

where the remainder  $R^m(b)$  is given by the *Stieltjes integral*

$$R^P(b) = (-1)^{P+1} \int_0^N D^P f(X_t) d\pi_{P+1}(Z_t(b)).$$

The result is obtained by repeating the *integration by parts*.

## Proposition (B., Friz, Paycha '24+)

For any  $b \in T_1^P(V)$

$$I_N(f, X) = \int_0^N f(Y_t) dX_t - [f(X_t) b^1]_{t=0}^N \\ + \sum_{l=2}^P (-1)^l [D^{l-1} f(X_t) \pi_l(Z_t(b))]_{t=0}^N + R^P(b)$$

where the remainder  $R^m(b)$  is given by the *Stieltjes integral*

$$R^P(b) = (-1)^{P+1} \int_0^N D^P f(X_t) d\pi_{P+1}(Z_t(b)).$$

The result is obtained by repeating the *integration by parts*.

# Three fundamental questions

Even if the formula appears to be the same as before, three main questions need to be understood:

- How can I best describe the sawtooth signature  $Z_t(b)$ ?
- How do you choose  $b$  to find periodic Bernoulli polynomials in a non-periodic context?
- What formula is obtained when  $R^p(b) = 0$ ?



It is natural to compare  $Z(b)$  with the **signature of the path**  $X$   
 $S(X): \{0 < s < t < N\} \rightarrow T_1((V))$

$$\pi_l(S_{s,t}(X)) = \int_{\Delta'_{s,t}} dX_{s_1} \otimes \cdots \otimes dX_{s_l} \quad \Delta'_{s,t} = \{s \leq s_1 \leq \cdots \leq s_l \leq t\}$$

The process  $t \rightarrow S_{s,t}(X)$  is the solution of the differential equation

$$\begin{cases} dS_{s,t}(X) = S_{s,t}(X) \otimes dX_t \\ S_{s,s}(X) = \mathbf{1} \end{cases}$$

and it is the basis for **rough paths**

It is natural to compare  $Z(b)$  with the **signature of the path**  $X$   
 $S(X): \{0 < s < t < N\} \rightarrow T_1((V))$

$$\pi_l(S_{s,t}(X)) = \int_{\Delta'_{s,t}} dX_{s_1} \otimes \cdots \otimes dX_{s_l} \quad \Delta'_{s,t} = \{s \leq s_1 \leq \cdots \leq s_l \leq t\}$$

The process  $t \rightarrow S_{s,t}(X)$  is the solution of the differential equation

$$\begin{cases} dS_{s,t}(X) = S_{s,t}(X) \otimes dX_t \\ S_{s,s}(X) = \mathbf{1} \end{cases}$$

and it is the basis for **rough paths**

Theorem (B., Friz, Paycha '24+)

For all  $b \in T_1((V))$  and  $l \geq 1$  we have the identity

$$\begin{aligned} \pi_l(Z_t(b)) = & (-1)^l \pi_l(S_{0,t}(X)^{-1}) \otimes b \\ & - \sum_{k=0}^{[t]} (-1)^{l-1} \pi_{l-1}(S_{k,t}(X)^{-1}) \otimes \delta X_k \end{aligned}$$

- The dependence of  $b$  is linear with respect to  $\otimes$ .
- $Z_t(b)$  is an algebraic functional of the signature.

Theorem (B., Friz, Paycha '24+)

For all  $b \in T_1((V))$  and  $l \geq 1$  we have the identity

$$\begin{aligned} \pi_l(Z_t(b)) = & (-1)^l \pi_l(S_{0,t}(X)^{-1}) \otimes b \\ & - \sum_{k=0}^{[t]} (-1)^{l-1} \pi_{l-1}(S_{k,t}(X)^{-1}) \otimes \delta X_k \end{aligned}$$

- The dependence of  $b$  is linear with respect to  $\otimes$ .
- $Z_t(b)$  is an algebraic functional of the signature.

To describe  $Z_t(b)$  we couple a classical induction with the study of the reversed signature  $t \rightarrow S_{s,t}^b(X)$  which solves

$$\begin{cases} dS_{s,t}^b(X) = dX_t \otimes S_{s,t}^b(X) \\ S_{s,s}(X) = \mathbf{1} \end{cases}$$

the components of  $S_{s,t}^b(X)$  are the **reversed iterated integrals**

$$\pi_l(S_{s,t}^b(X)) = \int_{\Delta_{0,t}^{l,*}} dX_{s_1} \otimes \cdots \otimes dX_{s_l}, \quad \Delta_{0,t}^{l,*} = \{0 \leq s_l < \dots < s_1 \leq t\}$$

We can calculate  $\pi_l(S_{s,t}^{flat}(X))$  using the relation

$$\pi_l(S_{s,t}^b(X)) = (-1)^l \pi_l(S_{s,t}(X)^{-1})$$

To describe  $Z_t(b)$  we couple a classical induction with the study of the reversed signature  $t \rightarrow S_{s,t}^b(X)$  which solves

$$\begin{cases} dS_{s,t}^b(X) = dX_t \otimes S_{s,t}^b(X) \\ S_{s,s}(X) = \mathbf{1} \end{cases}$$

the components of  $S_{s,t}^b(X)$  are the **reversed iterated integrals**

$$\pi_l(S_{s,t}^b(X)) = \int_{\Delta_{0,t}^{l,*}} dX_{s_1} \otimes \cdots \otimes dX_{s_l}, \quad \Delta_{0,t}^{l,*} = \{0 \leq s_l < \dots < s_1 \leq t\}$$

We can calculate  $\pi_l(S_{s,t}^{flat}(X))$  using the relation

$$\pi_l(S_{s,t}^b(X)) = (-1)^l \pi_l(S_{s,t}(X)^{-1})$$

# Optimal choice of initial constants

It is natural to look for the constant  $b$  which **minimises**  $R^P(b)$ .

By decomposing  $R^P$  **symmetrically** we apply **Cauchy-Schwarz**

$$\mathbb{E}\|R^P(b)\| \lesssim \left( \mathbb{E} \int_0^N \|\pi_p(Z_t(b))\|_{V^{\otimes p}}^2 |dX_t| \right)^{1/2}$$

with  $|dX_t|$  the **total variation** of the process

It is natural to look for the constant  $b$  which **minimises**  $R^P(b)$ .

By decomposing  $R^P$  **symmetrically** we apply **Cauchy-Schwarz**

$$\mathbb{E}\|R^P(b)\| \lesssim \left( \mathbb{E} \int_0^N \|\pi_p(Z_t(b))\|_{V^{\otimes p}}^2 |dX_t| \right)^{1/2}$$

with  $|dX_t|$  the **total variation** of the process



# Optimal choice of initial constants

As we are looking for a sequence of **universal constants**  $b \in T_1((V))$  we would like to define  $\pi_p(b)$  recursively

Definition (B., Friz, Paycha '24+)

For all  $l \geq 1$  we set

$$\pi_l(b^*) = -\frac{1}{\mathbb{E} \int_0^N |dX_t|} \mathbb{E} \int_0^N \pi_l(Z_t(b^{*, \langle l \rangle})) |dX_t|$$

where  $b^{*, \langle l \rangle} = (1, \pi_1(b^*), \dots, \pi_{l-1}(b^*), 0, \dots)$ . We call  $b^* \in T_1((V))$  the **optimal average constants**

# Optimal choice of initial constants

As we are looking for a sequence of **universal constants**  $b \in T_1((V))$  we would like to define  $\pi_p(b)$  recursively

**Definition (B., Friz, Paycha '24+)**

For all  $l \geq 1$  we set

$$\pi_l(b^*) = -\frac{1}{\mathbb{E} \int_0^N |dX_t|} \mathbb{E} \int_0^N \pi_l(Z_t(b^{*,<l})) |dX_t|$$

where  $b^{*,<l} = (1, \pi_1(b^*), \dots, \pi_{l-1}(b^*), 0, \dots)$ . We call  $b^* \in T_1((V))$  the **optimal average constants**

# Optimal choice of initial constants

Theorem (B., Friz, Paycha '24+)

When  $V$  is a Hilbert space the value  $\pi_l(b^*)$  *minimizes* for all  $l \geq 1$  the functional

$$v \in V^{\otimes l} \rightarrow \mathbb{E} \int_0^N \|\pi_l(Z_t(b^{*, <l} + v))\|_{V^{\otimes l}}^2 |dX_t|.$$

Thanks to the linear dependence of  $b$ , we can prove that

$$\begin{aligned} & \mathbb{E} \int_0^N \|\pi_l(Z_t(b^{*, <l} + v))\|_{V^{\otimes l}}^2 |dX_t| \\ &= \mathbb{E} \int_0^N \|\pi_l(Z_t(b^{*, <l})) + v\|_{V^{\otimes l}}^2 |dX_t| \end{aligned}$$

The result follows from the *optimisation of a quadratic functional*

## Theorem (B., Friz, Paycha '24+)

When  $V$  is a Hilbert space the value  $\pi_l(b^*)$  *minimizes* for all  $l \geq 1$  the functional

$$v \in V^{\otimes l} \rightarrow \mathbb{E} \int_0^N \|\pi_l(Z_t(b^{*, <l} + v))\|_{V^{\otimes l}}^2 |dX_t|.$$

Thanks to the linear dependence of  $b$ , we can prove that

$$\begin{aligned} & \mathbb{E} \int_0^N \|\pi_l(Z_t(b^{*, <l} + v))\|_{V^{\otimes l}}^2 |dX_t| \\ &= \mathbb{E} \int_0^N \|\pi_l(Z_t(b^{*, <l})) + v\|_{V^{\otimes l}}^2 |dX_t| \end{aligned}$$

The result follows from the *optimisation of a quadratic functional*

## Theorem (B.,Friz, Paycha '24+)

When  $X_t = t$  and  $V = \mathbb{R}$  for all  $l \geq 2$  we have

$$\pi_l(Z_t(b^*)) = Q_l(t)$$

The proof is derived by an **explicit calculation** and an **intrinsic property** of the Bernoulli numbers

In general, this choice should improve the **numerical efficiency** in the computation of Riemann-Stieltjes integrals.

Theorem (B.,Friz, Paycha '24+)

When  $X_t = t$  and  $V = \mathbb{R}$  for all  $l \geq 2$  we have

$$\pi_l(Z_t(b^*)) = Q_l(t)$$

The proof is derived by an **explicit calculation** and an **intrinsic property** of the Bernoulli numbers

In general, this choice should improve the **numerical efficiency** in the computation of Riemann-Stieltjes integrals.

# Zero Remainder in EML

A classical application of EML are the **Faulhaber formulas** when  $f(x) = x^q$ ,  $q \geq 1$  et  $p = q + 1$

$$\sum_{k=1}^{N-1} k^q = \frac{N^{q+1}}{q+1} + \sum_{l=1}^q \frac{B_l}{l!} \frac{q!}{(q-l+1)} N^{q-l+1}$$

When  $\mathbf{b} = \mathbf{1}$  et  $D^p f = 0$  the preliminary EML becomes

$$\int_0^N f(X_s) dX_s = \sum_{k=0}^{N-1} f(X_k) \delta X_k + \sum_{l=2}^p (-1)^{l+1} D^{l-1} f(X_N) \pi_l(Z_N(\mathbf{1}))$$

# Zero Remainder in EML

A classical application of EML are the **Faulhaber formulas** when  $f(x) = x^q$ ,  $q \geq 1$  et  $p = q + 1$

$$\sum_{k=1}^{N-1} k^q = \frac{N^{q+1}}{q+1} + \sum_{l=1}^q \frac{B_l}{l!} \frac{q!}{(q-l+1)} N^{q-l+1}$$

When  $\mathbf{b} = \mathbf{1}$  et  $D^p f = 0$  the preliminary EML becomes

$$\int_0^N f(X_s) dX_s = \sum_{k=0}^{N-1} f(X_k) \delta X_k + \sum_{l=2}^p (-1)^{l+1} D^{l-1} f(X_N) \pi_l(Z_N(\mathbf{1}))$$



When  $f(X)(Y) = X \otimes Y$

$$\begin{aligned} \int_{\Delta_{0,N}^2} dX_{s_1} \otimes dX_{s_2} &= \sum_{k=0}^{N-1} X_k \otimes \delta X_k - \pi_2(Z_N) \\ &= \sum_{0 \leq l < k < N} \delta X_l \otimes \delta X_k - \pi_2(Z_N) \end{aligned}$$

The term on the right involves the discrete signature of order 2 defined from the time series  $\{X_k\}_{k=0,\dots,N}$

The sawtooth signature can be seen as a correction between discrete and continuous signatures.

When  $f(X)(Y) = X \otimes Y$

$$\begin{aligned} \int_{\Delta_{0,N}^2} dX_{s_1} \otimes dX_{s_2} &= \sum_{k=0}^{N-1} X_k \otimes \delta X_k - \pi_2(Z_N) \\ &= \sum_{0 \leq l < k < N} \delta X_l \otimes \delta X_k - \pi_2(Z_N) \end{aligned}$$

The term on the right involves **the discrete signature of order 2** defined from the **time series**  $\{X_k\}_{k=0,\dots,N}$

The sawtooth signature can be seen as a **correction between discrete and continuous signatures.**

Given a time series  $x: \llbracket 0, N \rrbracket \rightarrow V$ , consider the iterated sums  $\Sigma(x): \{0 \leq m < n \leq N\} \rightarrow T_1((V))$

$$\pi_l(\Sigma_{m,n}(x)) = \sum_{m \leq j_1 < \dots < j_l < n} \delta x_{j_1} \otimes \dots \otimes \delta x_{j_l}$$

Unfortunately, these tensors are not sufficient to describe all possible products.

$$\begin{aligned} \pi_1(\Sigma_{0,N}(x)) \otimes \pi_1(\Sigma_{0,N}(x)) &= x_N - x_0 \otimes x_N - x_0 \\ &= \sum_{0 \leq l < k < N} \delta x_l \otimes \delta x_k + \sum_{0 \leq k < l < N} \delta x_l \otimes \delta x_k + \sum_{k=0}^{N-1} (\delta x_k)^{\otimes 2} \end{aligned}$$

Given a time series  $x: \llbracket 0, N \rrbracket \rightarrow V$ , consider the iterated sums  $\Sigma(x): \{0 \leq m < n \leq N\} \rightarrow T_1((V))$

$$\pi_l(\Sigma_{m,n}(x)) = \sum_{m \leq j_1 < \dots < j_l < n} \delta x_{j_1} \otimes \dots \otimes \delta x_{j_l}$$

Unfortunately, these tensors are not sufficient to describe all possible products.

$$\begin{aligned} \pi_1(\Sigma_{0,N}(x)) \otimes \pi_1(\Sigma_{0,N}(x)) &= x_N - x_0 \otimes x_N - x_0 \\ &= \sum_{0 \leq l < k < N} \delta x_l \otimes \delta x_k + \sum_{0 \leq k < l < N} \delta x_l \otimes \delta x_k + \sum_{k=0}^{N-1} (\delta x_k)^{\otimes 2} \end{aligned}$$

# Discrete Signatures

For any integer  $n > 0$  a composition of  $n$  is a vector  $I = (i_1, \dots, i_k)$  of positive integers s.t.  $i_1 + \dots + i_k = n$ .

$$\|I\| = \sum_{j=1}^k i_j, \quad |I| = k$$

Definition (DET 2020, BP2023)

We define the *discrete signature* as the value

$\{\Sigma^I(x) : \{0 \leq m < n \leq N\} \rightarrow V^{\otimes \|I\|}\}_{I \in \text{Composition}}$

$$\Sigma_{m,n}^I(x) = \sum_{m \leq j_1 < \dots < j_{|I|} < n} (\delta x_{j_1})^{\otimes i_1} \otimes \dots \otimes (\delta x_{j_{|I|}})^{\otimes i_{|I|}}$$

For any integer  $n > 0$  a composition of  $n$  is a vector  $I = (i_1, \dots, i_k)$  of positive integers s.t.  $i_1 + \dots + i_k = n$ .

$$\|I\| = \sum_{j=1}^k i_j, \quad |I| = k$$

Definition (DET 2020, BP2023)

We define the *discrete signature* as the value

$$\{\Sigma^I(x) : \{0 \leq m < n \leq N\} \rightarrow V^{\otimes \|I\|}\}_{I \in \text{Composition}}$$

$$\Sigma_{m,n}^I(x) = \sum_{m \leq j_1 < \dots < j_{|I|} < n} (\delta x_{j_1})^{\otimes i_1} \otimes \dots \otimes (\delta x_{j_{|I|}})^{\otimes i_{|I|}}$$

Theorem (Chen 1954, AFS 2019, DET 2020)

Let  $X^{lin}: [0, N] \rightarrow V$  be the linear interpolation of a time series  $x: \llbracket 0, N \rrbracket \rightarrow V$ . For any integer  $u \geq 1$  we have

$$\pi_u(S_{m,n}(X^{lin})) = \sum_{I \in C(u)} \frac{1}{i_1! \dots i_k!} \Sigma_{m,n}^I(x)$$

Thanks to a slight generalisation of the identity

$$\int_0^N f(X_s) dX_s = \sum_{k=0}^{N-1} f(X_k) \delta X_k + \sum_{l=2}^p (-1)^l D^{l-1} f(X_N) \pi_l(Z_N)$$

we can provide an alternative proof of this identity with possible extensions.

Theorem (Chen 1954, AFS 2019, DET 2020)

Let  $X^{lin}: [0, N] \rightarrow V$  be the linear interpolation of a time series  $x: \llbracket 0, N \rrbracket \rightarrow V$ . For any integer  $u \geq 1$  we have

$$\pi_u(S_{m,n}(X^{lin})) = \sum_{I \in C(u)} \frac{1}{i_1! \dots i_k!} \Sigma_{m,n}^I(x)$$

Thanks to a **slight generalisation** of the identity

$$\int_0^N f(X_s) dX_s = \sum_{k=0}^{N-1} f(X_k) \delta X_k + \sum_{l=2}^p (-1)^l D^{l-1} f(X_N) \pi_l(Z_N)$$

we can provide an **alternative proof** of this identity with **possible extensions**.



- Similar results can be obtained for right-point Riemann sums

$$\sum_{k=0}^{N-1} f(X_{k+1})\delta X_k$$

- Extension to **semimartingales**, **rough paths**.
- **Numerical simulations** of integrals?

谢谢!